+15 V Digital Potentiometers AD5260/AD5262

## FEATURES

256 Position
AD5260 - 1-Channel
AD5262 - 2-Channel (Independently Programmable)
Potentiometer Replacement
20K, 50K, 200K Ohm
3-Wire SPI Compatible Serial Data Input
+5 to +15 V Single-Supply; $\pm 5.5 \mathrm{~V}$ Dual-Supply Operation
Power ON Mid-Scale Preset

## APPLICATIONS

Mechanical Potentiometer Replacement
Instrumentation: Gain, Offset Adjustment
Programmable Voltage to Current Conversion
Programmable Filters, Delays, Time Constants
Line Impedance Matching

## GENERAL DESCRIPTION

The AD5260/AD5262 provides a single or dual channel, 256 position, digitally-controlled variable resistor (VR) device. These devices perform the same electronic adjustment function as a potentiometer or variable resistor. Each Channel of the AD5260/AD5262 contains a fixed resistor with a wiper contact that taps the fixed resistor value at a point determined by a digital code loaded into the SPI compatible serial-input register. The resistance between the wiper and either end point of the fixed resistor varies linearly with respect to the digital code transferred into the VR latch. The variable resistor offers a completely programmable value of resistance, between the A terminal and the wiper or the B terminal and the wiper. The fixed A to B terminal resistance of $20 \mathrm{~K}, 50 \mathrm{~K}$ or $200 \mathrm{~K} \Omega$ has a nominal temperature coefficient of 30 ppm $/{ }^{\circ} \mathrm{C}$.

Each VR has its own VR latch, which holds its programmed resistance value. These VR latches are updated from an internal serial-to-parallel shift register, which is loaded from a standard 3wire serial-input digital interface. The AD5260 contains an 8-bit serial register while the AD5262 contains a 9-bit serial register. Each bit is clocked into the register on the positive edge of the CLK. The AD5262 address bit determines the corresponding VR latch to be loaded with the last 8 -bits of the data word during the positive edging of $\overline{C S}$ strobe. A serial data output pin at the opposite end of the serial register enables simple daisy-chaining in multiple VR applications without additional external decoding logic.

An optional reset $(\overline{\mathrm{PR}})$ pin forces the wiper to the midscale position by loading $80_{\mathrm{H}}$ into the VR latch.

The AD5260/AD5262 are available ultra compact thin surface mount TSSOP-14 and 16. All parts are guaranteed to operate over the extended industrial temperature range of $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$.

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AD5260 FUNCTIONAL BLOCK DIAGRAM


AD5262 FUNCTIONAL BLOCK DIAGRAM
ORDERING GUIDE

|  | Kilo <br> Ohms | Temp | Package <br> Description | Package <br> Option |
| :--- | :--- | :--- | :--- | :--- |
| AD5260BRU20 | 20 | $-40 /+85^{\circ} \mathrm{C}$ | TSSOP-14 | RU-14 |
| AD5260BRU50 | 50 | $-40 /+85^{\circ} \mathrm{C}$ | TSSOP-14 | RU-14 |
| AD5260BRU200 | 200 | $-40 /+85^{\circ} \mathrm{C}$ | TSSOP-14 | RU-14 |
| AD5262BRU20 | 20 | $-40 /+85^{\circ} \mathrm{C}$ | TSSOP-16 | RU -16 |
| AD5262BRU50 | 50 | $-40 /+85^{\circ} \mathrm{C}$ | TSSOP-16 | RU -16 |
| AD5262BRU200 | 200 | $-40 /+85^{\circ} \mathrm{C}$ | TSSOP-16 | RU -16 |

[^0]
## 1-/2-Channel +15V Digital Potentiometers

ELECTRICAL CHARACTERISTICS 20K, 50K, 200K OHM VERSION $\left(\mathrm{V}_{\mathrm{DD}}=+5 \mathrm{~V}, \mathrm{v}_{\mathrm{SS}}=-5 \mathrm{~V}, \mathrm{v}_{\mathrm{L}}=+5 \mathrm{~V}\right.$, $\mathrm{V}_{\mathrm{A}}=+\mathrm{V}_{\mathrm{DD}}, \mathrm{V}_{\mathrm{B}}=0 \mathrm{~V},-40^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+85^{\circ} \mathrm{C}$ unless otherwise noted.)


## 1-/2-Channel +15V Digital Potentiometers

ELECTRICAL CHARACTERISTICS 20K, 50K, 200K OHM VERSION $\left(\mathrm{v}_{\mathrm{DD}}=+5 \mathrm{~V}, \mathrm{v}_{\mathrm{SS}}=-5 \mathrm{~V}, \mathrm{v}_{\mathrm{L}}=+5 \mathrm{~V}\right.$,
$\mathrm{V}_{\mathrm{A}}=+\mathrm{V}_{\mathrm{DD}}, \mathrm{V}_{\mathrm{B}}=0 \mathrm{~V},-40^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<+85^{\circ} \mathrm{C}$ unless otherwise noted.)


## NOTES:

1. Typicals represent average readings at $+25^{\circ} \mathrm{C}$ and $\mathrm{V}_{D D}=+5 \mathrm{~V}, \mathrm{~V}_{S S}=-5 \mathrm{~V}$.
2. Resistor position nonlinearity error R-INL is the deviation from an ideal value measured between the maximum resistance and the minimum resistance wiper positions. R-DNL measures the relative step change from ideal between successive tap positions. Parts are guaranteed monotonic. $I_{W}=V_{D D} / R$ for both $V_{D D}=+5 \mathrm{~V}, \mathrm{~V}_{S S}=-5 \mathrm{~V}$.
3. $\quad \mathrm{V}_{\mathrm{AB}}=\mathrm{V}_{\mathrm{DD}}$, Wiper $\left(\mathrm{V}_{\mathrm{W}}\right)=$ No connect
4. $\operatorname{INL}$ and $D N L$ are measured at $V_{w}$ with the $R D A C$ configured as a potentiometer divider similar to a voltage output $D / A$ converter. $V A=V_{D D}$ and $V_{B}=0 V$. DNL specification limits of $\pm 1$ LSB maximum are Guaranteed Monotonic operating conditions.
5. Resistor terminals $\mathrm{A}, \mathrm{B}, \mathrm{W}$ have no limitations on polarity with respect to each other.
6. Guaranteed by design and not subject to production test.
7. Measured at the Ax terminals. All Ax terminals are open circuited in shutdown mode.
8. Worst case supply current consumed when input all logic-input levels set at 2.4 V , standard characteristic of CMOS logic.
9. $P_{D I S S}$ is calculated from ( $l_{D D} \times V_{D D}$ ). CMOS logic level inputs result in minimum power dissipation.
10. All dynamic characteristics use $V_{D D}=+5 \mathrm{~V}, \mathrm{~V}_{S S}=-5 \mathrm{~V}, \mathrm{~V}_{\mathrm{L}}=+5 \mathrm{~V}$
11. Measured at a $\mathrm{V}_{\mathrm{W}}$ pin where an adjacent $\mathrm{V}_{\mathrm{W}}$ pin is making a full-scale voltage change.
12. See timing diagram for location of measured values. All input control voltages are specified with $\mathrm{t}_{\mathrm{R}}=\mathrm{t}_{\mathrm{F}}=2 \mathrm{~ns}(10 \%$ to $90 \%$ of $+3 \mathrm{~V})$ and timed from a voltage level of 1.5 V . Switching characteristics are measured using $\mathrm{V}_{\mathrm{L}}=+5 \mathrm{~V}$.
13. Propagation delay depends on value of $\mathrm{V}_{\mathrm{DD}}, \mathrm{R}_{\mathrm{L}}$, and $\mathrm{C}_{\mathrm{L}}$ see applications text.
14. The AD5260/AD5262 contains 1,968 transistors. Die Size: 89 mil x 105 mil, 9,345 sq. mil.

## 1-/2-Channel +15V Digital Potentiometers

ABSOLUTE MAXIMUM RATINGS $\left(\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right.$, unless otherwise noted)
$\qquad$
$\mathrm{V}_{\text {SS }}$ to GND ............................................................... $0 \mathrm{~V},-7 \mathrm{~V}$
$\mathrm{V}_{\mathrm{DD}}$ to $\mathrm{V}_{\text {SS }} . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . ~+15 \mathrm{~V}$
$\mathrm{V}_{\mathrm{A}}, \mathrm{V}_{\mathrm{B}}, \mathrm{V}_{\mathrm{W}}$ to GND................................................ $\mathrm{V}_{\mathrm{SS}}, \mathrm{V}_{\mathrm{DD}}$
$\mathrm{A}_{\mathrm{X}}-\mathrm{B}_{\mathrm{X}}, \mathrm{A}_{\mathrm{X}}-\mathrm{W}_{\mathrm{X}}, \mathrm{B}_{\mathrm{X}}-\mathrm{W}_{\mathrm{X}} \ldots \ldots . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . ~ 20 m A ~$
Digital Inputs \& Output Voltage to GND................... $0 \mathrm{~V},+7 \mathrm{~V}$
Operating Temperature Range......................... $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Maximum Junction Temperature ( $\mathrm{T}_{\mathrm{J}}$ MAX) $. . . . . . . . . . . . . . . . . . ~+~ 1500^{\circ} \mathrm{C}$
Storage Temperature..................................... $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Lead Temperature (Soldering, 10 sec ).......................... $+300^{\circ} \mathrm{C}$
Thermal Resistance ${ }^{*} \theta_{\mathrm{JA}}$,

> TSSOP-14............................................................................................................ $180^{\circ} \mathrm{C} / \mathrm{W}$ TSSOP-16............ "Package Power Dissipation $=\left(\mathrm{T}_{J} \mathrm{MAX}-\mathrm{T}_{\mathrm{A}}\right) / \theta_{\mathrm{JA}}$

TABLE 1A: AD5260 Serial-Data Word Format

| DATA |  |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| MSB |  |  |  |  |  |  | LSB |
| $2^{7}$ |  |  |  |  |  |  | $2^{0}$ |

TABLE 1B: AD5262 Serial-Data Word Format

| ADDR | DATA |  |  |  |  |  |  | B6 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| B8 | B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
| A0 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|  | MSB |  |  |  |  |  |  | LSB |
| $2^{8}$ | $2^{7}$ |  |  |  |  |  |  | $2^{0}$ |



Figure 1A. Timing Diagram


Figure 1B. Detail Timing Diagram


Figure 1C. AD5260 Preset Timing Diagram

AD5260 PIN CONFIGURATION

| A1 1 | 14 | SDO |
| :---: | :---: | :---: |
| w1 2 | 13 | NC |
| B1 3 | 12 | $\mathrm{V}_{\mathrm{L}}$ |
| $\mathrm{V}_{\text {DD }} 4$ | 11 | $\mathrm{V}_{\text {ss }}$ |
| SHDN 5 | 10 | GND |
| CLK ${ }^{6}$ | 9 | PR |
| SDI ${ }^{7}$ | 8 | CS |

TABLE 2: AD5260 PIN Descriptions

| Pin | Name | Description |
| :---: | :---: | :---: |
| 1 | A | A Terminal |
| 2 | W | Wiper, addr $=0_{2}$ |
| 3 | B | B Terminal |
| 4 | $\mathrm{V}_{\mathrm{DD}}$ | Positive power supply, specified for operation at both +5 V or 15 V . (Sum of $\left\|\mathrm{V}_{\mathrm{DD}}\right\|+\left\|\mathrm{V}_{\mathrm{SS}}\right\| \leq 15 \mathrm{~V}$ ) |
| 5 | $\overline{\text { SHDN }}$ | Active low input. Terminal A opencircuit. Shutdown controls Variable Resistors of RDAC |
| 6 | CLK | Serial Clock Input, positive edge triggered |
| 7 | SDI | Serial Data Input |
| 8 | $\overline{\text { CS }}$ | Chip Select Input, Active Low. When $\overline{\mathrm{CS}}$ returns high, data will be loaded into the DAC register. |
| 9 | $\overline{\mathrm{PR}}$ | Active low preset to mid-scale; sets RDAC registers to $80_{\mathrm{H}}$ |
| 10 | GND | Ground |
| 11. | $\mathrm{V}_{\text {SS }}$ | Negative Power Supply, specified for operation from 0 V to -5 V |
| 12 | $\mathrm{V}_{\mathrm{L}}$ | Logic Supply Voltage, needs to be same voltage as the digital logic controlling the AD5260. |
| 13 | NC | No Connect |
| 14 | SDO | Serial Data Output, Open Drain transistor requires pull-up resistor. |

## AD5262 PIN CONFIGURATION



TABLE 3: AD5262 PIN Descriptions

| Pin | Name | Description |
| :---: | :---: | :---: |
| 1 | SDO | Serial Data Output, Open Drain transistor requires pull-up resistor. |
| 2 | A1 | A Terminal RDAC \#1 |
| 3 | W1 | Wiper RDAC \#1, address A0 $=0_{2}$ |
| 4 | B1 | B Terminal RDAC \#1 |
| 5 | $\mathrm{V}_{\mathrm{DD}}$ | Positive power supply, specified for operation at both +5 V or +15 V . (Sum of $\left\|\mathrm{V}_{\mathrm{DD}}\right\|+\left\|\mathrm{V}_{\mathrm{SS}}\right\| \leq 15 \mathrm{~V}$ ) |
| 6 | $\overline{\text { SHDN }}$ | Active low input. Terminal A opencircuit. Shutdown controls Variable Resistors \#1 through \#2 |
| 7 | CLK | Serial Clock Input, positive edge triggered |
| 8 | SDI | Serial Data Input |
| 9 | $\overline{C S}$ | Chip Select Input, Active Low. When $\overline{\mathrm{CS}}$ returns high, data in the serial input register is decoded based on the address bits and loaded into the target DAC register. |
| 10 | $\overline{\mathrm{PR}}$ | Active low preset to mid-scale; sets RDAC registers to $80_{\mathrm{H}}$ |
| 11 | GND | Ground |
| 12 | $\mathrm{V}_{\text {SS }}$ | Negative Power Supply, specified for operation at both 0 V or -5 V (Sum of $\left\|\mathrm{V}_{\mathrm{DD}}\right\|+\left\|\mathrm{V}_{\text {SS }}\right\|<15 \mathrm{~V}$ ) |
| 13 | $\mathrm{V}_{\mathrm{L}}$ | Logic Supply Voltage, needs to be same voltage as the digital logic controlling the AD5262. |
| 14 | B2 | B Terminal RDAC \#2 |
| 15 | W2 | Wiper RDAC \#2, address A $0=12$ |
| 16 | A2 | A Terminal RDAC \#2 |

## OPERATION

The AD5260/AD5262 provide a single/dual channel, 256position digitally-controlled variable resistor (VR) device. Changing the programmed VR settings is accomplished by clocking in a 9-bit serial data word into the SDI (Serial Data Input) pin. The format of this data word is one address bit A0 represents the first bit B8, then followed by eight data bits B7B0 with MSB first. Table 1 provides the serial register data word format. See Table 5 for the AD5260/AD5262 address assignments to decode the location of VR latch receiving the serial register data in bits B7 through B0. VR outputs can be changed one at a time in random sequence. The
AD5260/AD5262 presets to a mid-scale by asserting the $\overline{\text { PR }}$ pin, simplifying fault condition recovery at power up. Both parts have an internal power ON preset that places the wiper in a midscale preset condition at power ON. Operation of the power on preset function depends only on the logic pin $\left(\mathrm{V}_{\mathrm{L}}\right)$.
The AD5260/AD5262 contains a power shutdown $\overline{\text { SHDN }}$ pin, which places the RDAC in a zero power consumption state where terminals Ax are open circuited, and the wiper W is connected to B resulting in only leakage currents being consumed in the VR structure. In shutdown mode the VR latch settings are maintained, so that, returning to operational mode from power shutdown, the VR settings return to their previous resistance values.

## DIGITAL INTERFACING

The AD5260/AD5262 contain a standard three-wire serial input control interface. The three inputs are clock (CLK), $\overline{\mathrm{CS}}$ and serial data input (SDI). The positive-edge sensitive CLK input requires clean transitions to avoid clocking incorrect data into the serial input register. Standard logic families work well. If mechanical switches are used for product evaluation they should be debounced by a flip-flop or other suitable means. Figure 3 block diagram shows more detail of the internal digital circuitry. When $\overline{\mathrm{CS}}$ is low, the clock loads data into the serial register on each positive clock edge, see Table 4.


Figure 3. Block Diagram

## TABLE 4: Input Logic Control Truth Table

| CLK $\overline{\mathrm{CS}}$ | $\overline{\mathrm{PR}}$ | $\overline{\mathrm{SHDN}}$ | Register Activity |
| :--- | :--- | :--- | :--- |

L L $\quad$ H $\quad$ H $\quad$ No SR effect, enables SDO pin
P $\quad$ L $\quad H \quad H \quad$ Shift One bit in from the SDI pin. The eighth previously entered bit is shifted out of the SDO pin.
X $\quad$ P $\quad \mathrm{H} \quad \mathrm{H} \quad$ Load SR data into RDAC latch based on A0 decode (Table 5).
X $\quad$ H $\quad$ H $\quad$ H $\quad$ No Operation
X $\quad$ X $\quad$ L $\quad$ H $\quad$ Sets all RDAC latches to midscale, wiper centered, \& SDO latch cleared.
X $\quad$ H $\quad$ P $\quad$ H $\quad$ Latches all RDAC latches to $80_{H}$. X H H L Open circuits all resistor A-terminals, connects W to B, turns off SDO output transistor.

NOTE: $\mathrm{P}=$ positive edge, $\mathrm{X}=$ don't care, $\mathrm{SR}=$ shift register
The serial-data-output (SDO) pin contains an open drain nchannel FET. This output requires a pull-up resistor in order to transfer data to the next package's SDI pin. The pull-up resistor termination voltage may be larger than the $\mathrm{V}_{\mathrm{DD}}$ supply of the AD5260/AD5262 SDO output device, e.g., the AD5260/AD5262 could operate at $\mathrm{V}_{\mathrm{DD}}=3.3 \mathrm{~V}$ and the pull-up for interface to the next device could be set at +5 V . This allows for daisy chaining several RDACs from a single processor serial-data line. Clock period needs to be increased when using a pull-up resistor to the SDI pin of the following device in series. Capacitive loading at the daisy chain node SDO-SDI between devices may induce time delay to subsequent devices. User should be aware of this potential problem in order to achieve data transfer successfully. When daisy chaining is used, the $\overline{\mathrm{CS}}$ should be kept low until all the bits of every package are clocked into their respective serial registers insuring that the address bit and data bits are in the proper decoding location, see Figure 4. This would require 18 bits of address and data complying to the word format provided in Table 1 if two AD5262 RDACs are daisy chained. During shutdown (SHDN) the SDO output pin is forced to the off (logic high state) to disable power dissipation in the pull up resistor. See figure 6 for equivalent SDO output circuit schematic.


Figure 4. Daisy Chain Configuration

| TABLE 5. Address Decode Table |  |  |
| :--- | :--- | :--- |
| A0 | Latch Loaded |  |
| 0 | RDAC\#1 | AD5262 |
| 1 | RDAC\#2 | AD5262 |
| X | RDAC\#1 | AD5260 |

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Information contained in this Preliminary data sheet describes a product in the development stage. There is no guarantee that the information contained here will become a final product in its present form. For latest information contact Walt Heinzer/Analog Devices TEL(408)382-3107; walt.heinzer@analog.com

The data setup and data hold times in the specification table determine the data valid time requirements. The AD5260 uses an 8-bit serial input data register word that is transferred to the internal RDAC register when the CS line returns to logic high. For AD5262 the last 9 bits of the data word entered into the serial register are held when $\overline{\mathrm{CS}}$ returns high. Any extra bits are ignored. At the same time $\overline{\mathrm{CS}}$ goes high it gates the address decoder enabling AD5262 one of two positive edge triggered AD5262 RDAC latches, see figure 5 detail.


Figure 5. Equivalent Input Control Logic
The target RDAC latch is loaded with the last eight bits of the serial data word completing one DAC update. For AD5262, two separate 9 bit data words must be clocked in to change both VR settings.


Figure 6. Detail SDO output schematic of the AD5260
All digital inputs are protected with a series input resistor and parallel Zener ESD structure shown in figure 8. Applies to digital input pins $\overline{\mathrm{CS}}, \mathrm{SDI}, \mathrm{SDO}, \overline{\mathrm{PR}}, \overline{\mathrm{SHDN}}, \mathrm{CLK}$


Figure 7. ESD Protection of digital pins


Figure 8. ESD Protection of Resistor Terminals


Figure 9. AD5260/AD5262 Equivalent RDAC Circuit

## PROGRAMMING THE VARIABLE RESISTOR Rheostat Operation

The nominal resistances of the RDAC between terminals A and B are available with values of $20 \mathrm{~K} \Omega, 50 \mathrm{~K} \Omega$, and $200 \mathrm{~K} \Omega$. The final three digits of the part number determine the nominal resistance value, e.g. $20 \mathrm{~K} \Omega=20 ; 50 \mathrm{~K} \Omega=50 ; 200 \mathrm{~K} \Omega=200$. The nominal resistance ( $\mathrm{R}_{\mathrm{AB}}$ ) of the VR has 256 contact points accessed by the wiper terminal, plus the B terminal contact. The eight bit data in the RDAC latch is decoded to select one of the 256 possible settings. Assume a $20 \mathrm{~K} \Omega$ part is used, the wiper's first connection starts at the B terminal for data $00_{\mathrm{H}}$. Since there is a $60 \Omega$ wiper contact resistance, such connection yields a minimum of $60 \Omega$ resistance between terminals W and B . The second connection is the first tap point corresponds to $138 \Omega$ $\left(\mathrm{R}_{\mathrm{WB}}=\mathrm{R}_{\mathrm{AB}} / 256+\mathrm{R}_{\mathrm{W}}=78 \Omega+60 \Omega\right)$ for data $01_{\mathrm{H}}$. The third connection is the next tap point representing $216 \Omega(78 \times 2+60)$ for data $02_{\mathrm{H}}$ and so on. Each LSB data value increase moves the wiper up the resistor ladder until the last tap point is reached at $19982 \Omega\left[\mathrm{R}_{A B}-1 \mathrm{LSB}+\mathrm{R}_{\mathrm{w}}\right]$. The wiper does not directly connect to the B terminal. See Figure 9 for a simplified diagram of the equivalent RDAC circuit.

The general equation determining the digitally programmed output resistance between W and B is:
$R_{W B}(D)=\frac{D}{256} \cdot R_{A B}+R_{W}$
eqn. 1
where D is the decimal equivalent of the binary code which is loaded in the 8 -bit RDAC register, and $\mathrm{R}_{\mathrm{AB}}$ is the nominal end-to-end resistance.

For example, $\mathrm{R}_{A B}=20 \mathrm{~K} \Omega$, when $\mathrm{V}_{\mathrm{B}}=0 \mathrm{~V}$ and A-terminal is open circuit, the following output resistance values $R_{\text {wB }}$ will be set for the following RDAC latch codes. Result will be the same if terminal A is tied to W :

| D <br> $(\mathrm{DEC})$ | $\mathrm{R}_{\mathrm{WB}}$ <br> $(\mathrm{Ohms})$ | Output State |
| :--- | :--- | :--- |
|  |  |  |
| 256 | $199826 \Omega$ | Full-Scale $\left(\mathrm{R}_{\mathrm{AB}}-1 \mathrm{LSB}+\mathrm{R}_{\mathrm{w}}\right)$ |
| 128 | $10060 \Omega$ | Mid-Scale |
| 1 | $138 \Omega$ | 1 LSB |
| 0 | $60 \Omega$ | Zero-Scale (Wiper contact resistance) |

In the zero-scale condition a finite wiper resistance of $60 \Omega$ is present. Care should be taken to limit the current flow between W and B in this state to a maximum current of no more than 5 mA . Otherwise, degradation or possible destruction of the internal switch contact can occur.

Similar to the mechanical potentiometer, the resistance of the RDAC between the wiper W and terminal A also produces a digitally controlled resistance $\mathrm{R}_{\text {WA }}$. When these terminals are used the B-terminal should be let open or tied to the wiper terminal. Setting the resistance value for $\mathrm{R}_{\mathrm{WA}}$ starts at a maximum value of resistance and decreases as the data loaded in the latch is increased in value. The general equation for this operation is:

$$
\begin{equation*}
R_{W A}(D)=\frac{256-D}{256} \cdot R_{A B}+R_{W} \tag{eqn. 2}
\end{equation*}
$$

For example, $R_{A B}=20 \mathrm{~K} \Omega$, when $V_{A}=0 \mathrm{~V}$ and B -terminal is open, the following output resistance $\mathrm{R}_{\mathrm{wA}}$ will be set for the following RDAC latch codes. Result will be the same if terminal B is tied to W:

| D <br> $(\mathrm{DEC})$ | $\mathrm{R}_{\mathrm{WA}}$ <br> $(\Omega)$ | Output State |
| :--- | :--- | :--- |
|  |  |  |
| 256 | 60 | Full-Scale |
| 128 | 10060 | Mid-Scale |
| 1 | 19982 | 1 LSB |
| 0 | 20060 | Zero-Scale |

The typical distribution of the nominal resistance $\mathrm{R}_{\mathrm{AB}}$ from channel-to-channel matches within $\pm 1 \%$. Device to device matching is process lot dependent and is possible to have $\pm 30 \%$ variation. Since the resistance element is processed in thin film technology, the change in $\mathrm{R}_{\mathrm{AB}}$ with temperature has a 30 $\mathrm{ppm} /{ }^{\circ} \mathrm{C}$ temperature coefficient.

## PROGRAMMING THE POTENTIOMETER DIVIDER Voltage Output Operation

The digital potentiometer easily generates output voltages at wiper-to-B and wiper-to-A to be proportional to the input voltage at A-to-B. Let's ignore the effect of the wiper resistance at the moment. For example connecting A-terminal to +5 V and B -terminal to ground produces an output voltage at the wiper-to-B starting at zero volts up to 1 LSB less than +5 V . Each LSB
of voltage is equal to the voltage applied across terminal AB divided by the 256 position of the potentiometer divider. Since the AD5260/AD5262 operates from dual supplies, the general equation defining the output voltage at $\mathrm{V}_{\mathrm{w}}$ with respect to ground for any given input voltage applied to terminals $A B$ is:
$V_{W}(D)=\frac{D}{256} V_{A}+\frac{256-D}{256} V_{B} \quad$ eqn. 3
where D is decimal equivalent of the binary code, which is loaded in the 8 -bit RDAC register.

Operation of the digital potentiometer in the divider mode results in more accurate operation over temperature. Unlike the rheostat mode, the output voltage is dependent on the ratio of the internal resistors $\mathrm{R}_{\mathrm{wA}}$ and $\mathrm{R}_{\mathrm{wB}}$ and not the absolute values, therefore, the drift reduces to $5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$.

## TEST CIRCUITS

Figures 10 to 18 define the test conditions used in product specification table.


Figure 10. Potentiometer Divider Nonlinearity error test circuit (INL, DNL)


Figure 11. Resistor Position Nonlinearity Error (Rheostat Operation; R-INL, R-DNL)


Figure 12. Wiper Resistance test Circuit


Figure 13. Power supply sensitivity test circuit (PSS, PSSR)


Figure 14. Inverting Gain test Circuit

OUTLINE DIMENSIONS
Dimensions shown in inches and (mm)



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