### **GENERAL DESCRIPTION**

The TDA1023 is a bipolar integrated circuit for controlling triacs in the time proportional or burst firing mode. It permits very precise temperature control of heating equipment and is especially suited for the control of panel heaters. The circuit generates positive-going trigger pulses and complies with the regulations on radio interference and mains distortion.

### Special features are:

- adjustable proportional range width
- adjustable hysteresis
- adjustable trigger pulse width
- adjustable firing burst repetition time
- · control range translation facility
- failsafe operation
- supplied from the mains
- provides supply for external temperature bridge

### QUICK REFERENCE DATA

Supply voltage (derived from mains voltage)	Vcc	typ.	13.7 V
Stabilized supply voltage for temperature bridge	٧z	typ.	8 V
Supply current (average value)	<sup> </sup> 16(AV)	typ.	10 mA
Trigger pulse width	t <sub>W</sub>	typ.	200 μs
Firing burst repetition time at $C_T$ = 68 $\mu$ F	$T_b$	typ.	41 s
Output current	- <sup>1</sup> он*	max.	150 mA
Operating ambient temperature range	Tamb	-20 to	o + 75 °C

Negative current is defined as conventional current flow out of a device. A negative output current is suited for positive triac triggering.

### PACKAGE OUTLINE

16-lead DIL; plastic (SOT-38).

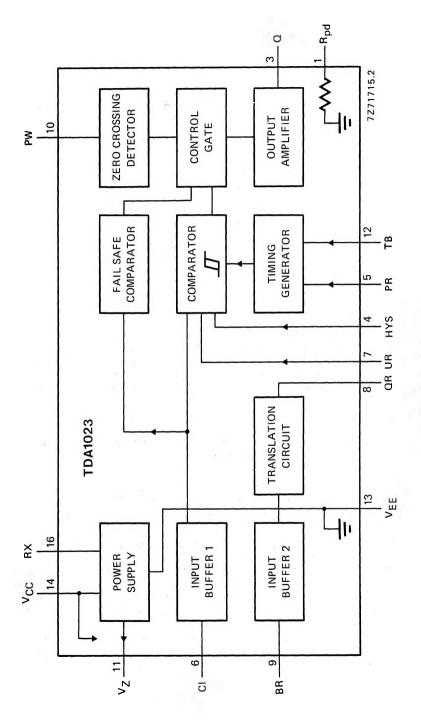


Fig. 1 Block diagram.

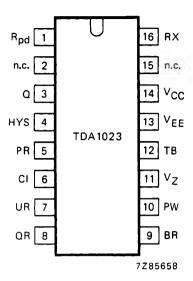


Fig. 2 Pinning diagram.

#### **PINNING** internal pull-down resistor connection Rnd 2 n.c. not connected 3 Q output HYS hysteresis control input PR 5 proportional range control input 6 CI Control input UR 7 unbuffered reference input 8 OR output of reference buffer BR 9 buffered reference input 10 PW pulse width control input 11 ٧7 reference supply output 12 TB firing burst repetition time control input 13 VFF ground connection 14 positive supply connection Vcc 15 n.c. not connected

external resistor connection

#### **FUNCTIONAL DESCRIPTION**

The TDA1023 generates pulses to trigger a triac. These trigger pulses coincide with the zero crossings of the mains voltage. This minimizes r.f. interference and transients on the mains supply. The trigger pulses come in bursts, with the net effect that the load is periodically switched on and off. This further minimizes mains pollution. The average power in the load is varied by varying the duration of the trigger pulse burst, in accordance with the voltage difference between the control input Cl and the reference input, either UR or BR.

16 RX

Power supply: VCC, RX and Vz (pins 14, 16 and 11)

The TDA1023 is supplied from the a.c. mains via a resistor  $R_D$  to the RX connection (pin 16); the  $V_{EE}$  connection (pin 13) is connected to the neutral line (see Fig. 4a). A smoothing capacitor  $C_S$  has to be connected between the  $V_{CC}$  and  $V_{EE}$  connections.

The circuit contains a string of stabilizer diodes between the RX and  $V_{EE}$  connections that limit the d.c. supply voltage, and a rectifier diode between the RX and  $V_{CC}$  connections (see Fig. 3).

At pin 11 the device provides a stabilized reference voltage  $V_Z$  for an external temperature sensing bridge.

The operation of the supply arrangement is as follows. During the positive half of the mains cycles the current through external voltage dropping resistor  $R_D$  charges the external smoothing capacitor  $C_S$  until RX reaches the stabilizing voltage of the internal stabilizer diodes.  $R_D$  should be chosen such that it can supply the current  $I_{CC}$  for the TDA1023 itself plus the average output current  $I_{3(AV)}$  plus the current required from the  $V_Z$  connection for an external temperature bridge, and recharge the smoothing capacitor  $C_S$  (see Figs 9 to 12). Any excess current is bypassed by the internal stabilizer diodes. Note that the maximum rated supply current must not be exceeded.

During the negative half of the mains cycles external smoothing capacitor C<sub>S</sub> has to supply the sum of the currents mentioned above. Its capacitance must be high enough to maintain the supply voltage above the minimum specified limit.

### **FUNCTIONAL DESCRIPTION** (continued)

Dissipation in resistor R<sub>D</sub> is halved by connecting a diode in series (see Fig. 4b and 9 to 12).

A further reduction of dissipation is possible by using a high-quality voltage dropping capacitor C<sub>D</sub> in series with a resistor R<sub>SD</sub> (see Figs 4c and 14). Asuitable VDR connected across the mains provides protection of the TDA1023 and of the triac against mains-borne transients.

### Control and reference inputs CI, BR and UR (pins 6, 9 and 7)

For room temperature control (5 °C to 30 °C) the best performance is obtained by using the translation circuit. The buffered reference input BR (pin 9) is used as a reference input, and the output of the reference buffer QR (pin 8) is connected to the unbuffered reference input UR (pin 7). In this arrangement the translation circuit ensures that most of the potentiometer rotation can be used to cover the room temperature range. This provides an accurate temperature setting and a linear temperature scale.

If the translation circuit is not required, the unbuffered reference input UR (pin 7) is used as a reference input. The buffered reference input BR (pin 9) must be connected to the reference supply output V<sub>7</sub> (pin 11).

For proportional power control the unbuffered reference input UR (pin 7) must be connected to the firing burst repetition time control input TB (pin 12) and the buffered reference input BR (pin 9), which is inactive now, must be connected to the reference supply output  $\sqrt{2}$  (pin 11).

In all arrangements the train of output pulses becomes longer when the voltage at the control input CI (pin 6) becomes lower.

### Proportional range control input PR (pin 5)

With the proportional range control input PR open the output duty factor changes from 0% to 100% by a variation of 80 mV at the control input CI (pin 6). For temperature control this corresponds with a temperature difference of only 1 K.

This range may be increased to 400 mV, i.e. 5 K, by connecting the proportional range control input PR (pin 5) to ground. Intermediate values are obtained by connecting the PR input to ground via a resistor R5, see Table 1.

### Hysteresis control input HYS (pin 4)

With the hysteresis control input HYS (pin 4) open the device has a built-in hysteresis of 20 mV. For temperature control this corresponds with 0.25 K.

Hysteresis is increased to 320 mV, corresponding with 4 K, by grounding HYS (pin 4). Intermediate values are obtained by connecting pin 4 to ground via a resistor R4. See Table 1 for a set of values for R4 and R5 giving a fixed ratio between hysteresis and proportional range.

### Trigger pulse width control input PW (pin 10)

The trigger pulse width may be adjusted to the value required for the triac by choosing the value of the external synchronization resistor R<sub>S</sub> between the trigger pulse width control input PW (pin 10) and the a.c. mains. The pulse width is inversely proportional to the input current (see Fig. 13).

#### Output Q (pin 3)

Since the circuit has an open-emitter output, it is capable of sourcing current, i.e. supplying a current out of the output. Therefore it is especially suited for generating positive-going trigger pulses. The output is current-limited and protected against short-circuits. The maximum output current is 150 mA and the output pulses are stabilized at 10 V for output currents up to that value.

### **FUNCTIONAL DESCRIPTION** (continued)

A gate resistor  $R_G$  must be connected between the output Q and the triac gate to limit the output current to the minimum required by the triac (see Figs 5 to 8). This minimizes the total supply current and the power dissipation.

## Pull-down resistor Rpd (pin 1)

The TDA1023 includes a 1.5 k $\Omega$  pull-down resistor R<sub>pd</sub> between pins 1 and 13 (V<sub>EE</sub>, ground connection), intended for use with sensitive triacs.

### **RATINGS**

Limiting values in accordance with the	e Absolute Maximum System	(IEC 134)
--	---------------------------	-----------

Supply voltage, d.c.	$v_{CC}$	max.	16 V
Supply current			
average	<sup>I</sup> 16(AV)	max.	30 mA
repetitive peak	<sup>l</sup> 16(RM)	max.	100 mA
non-repetitive peak	<sup>1</sup> 16(SM)	max.	2 A
Input voltage, all inputs	$v_1$	max.	16 V
Input current, CI, UR, BR, PW input	<sup>l</sup> 6; 7; 9; 10	max.	10 mA
Voltage on R <sub>pd</sub> connection	V <sub>1</sub>	max.	16 V
Output voltage, Q, QR, VZ output	V <sub>3; 8; 11</sub>	max.	16 V
Output current			
average	−loh(AV)	max.	30 mA
peak, max. 300 $\mu$ s	-IOH(M)	max.	700 mA
Total power dissipation	P <sub>tot</sub>	max.	500 mW
Storage temperature range	T <sub>stg</sub>	-55 to	+150 °C
Operating ambient temperature range	T <sub>amb</sub>	-20 to	+ 75 °C

### **CHARACTERISTICS**

 $V_{CC}$  = 11 to 16 V;  $T_{amb}$  = -20 to + 75 °C unless otherwise specified

	symbol	min.	typ.	max.	unit
Supply: V <sub>CC</sub> and RX (pins 14 and 16)					
Internally stabilized supply voltage	i				
at I <sub>16</sub> = 10 mA	Vcc	12	13.7	15	V
Variation with 1 <sub>16</sub>	ΔV <sub>CC</sub> /ΔI <sub>16</sub>	-	30	_	mV/mA
Supply current at $V_{16-13} = 11$ to 16 V;					
I <sub>10</sub> = 1 mA; f = 50 Hz; pin 11 open; V <sub>6-13</sub> > V <sub>7-13</sub> ; pins 4 and 5 open	116	_	_	6	mA
pins 4 and 5 grounded	116		_	7.1	mA
pins 4 and 5 grounded	'16	ļ		•••	'''' '
Reference supply output V <sub>Z</sub> (pin 11) for external temperature bridge					
Output voltage	V11-13	-	8	_	٧
Output current	-111	_	-	1	mA
Control and reference inputs CI, BR and UR (pins 6, 9 and 7)					
Input voltage to inhibit the output	V <sub>6-13</sub>	-	7.6		V
Input current at V <sub>I</sub> = 4 V	l <sub>6</sub> ; 7; 9	_	-	2	μΑ
Hysteresis control input HYS (pin 4)					
Hysteresis, pin 4 open	Δν <sub>6</sub>	9	20	40	mV
pin 4 grounded	ΔV6	_	320	_	mV
Proportional range control input PR (pin 5)					
Proportional range, pin 5 open	Δν <sub>6</sub>	50	80	130	mV
pin 5 grounded	Δν <sub>6</sub>	_	<b>40</b> 0	_	mV
Pulse width control input PW (pin 10)					
Pulse width at I <sub>10</sub> (RMS) = 1 mA; f = 50 Hz	t <sub>w</sub>	100	200	300	μs
Firing burst repetition time control input TB	·w	100	200	555	
(pin 12)					
Firing burst repetition time,					
ratio to capacitor C <sub>T</sub>	T <sub>b</sub> /C <sub>T</sub>	320	600	960	ms/μF
Output of reference buffer QR (pin 8)					
Output voltage		_			
at input voltage V <sub>9-13</sub> = 1.6 V	V8-13	-	3.2	=	V
V <sub>9-13</sub> = 4.8 V	V8-13	_	4.8	_	V
V <sub>9-13</sub> = 8 V	V8-13	_	6.4	_	V

	symbol	min.	typ.	max.	unit
Output Q (pin 3)					
Output voltage HIGH at -IOH = 150 mA	$v_{OH}$	10	-	-	V
Output current HIGH	-loh	_	_	150	mA
Internal pull-down resistor Rpd (pin 1)					
Resistance to VEE	$R_{pd}$	1	1.5	3	kΩ

Table 1. Adjustment of proportional range and hysteresis. Combinations of resistor values giving hysteresis > ½ proportional range.

proportional range	proportional range resistor R5 kΩ	minimum hysteresis mV	maximum hysteresis resistor R4 kΩ
80	open	20	open
160	3.3	40	9.1
240	1.1	60	4,3
320	0.43	80	2.7
400	0	100	1.8

Table 2. Timing capacitor C<sub>T</sub> values.

effective d.c. value	marked a.c. specification		catalogue number*
μF	μF	٧	
68 47 33 22 15	47 33 22 15 10 6.8	25 40 25 40 25 40 25 40	2222 016 90129 - 90131 - 015 90102 - 90101 - 90099 - 90098

<sup>\*</sup> Special electrolytic capacitors recommended for use with TDA1023.

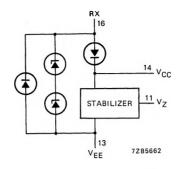


Fig. 3 Internal supply connections.

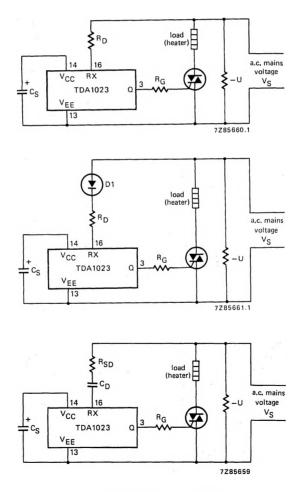
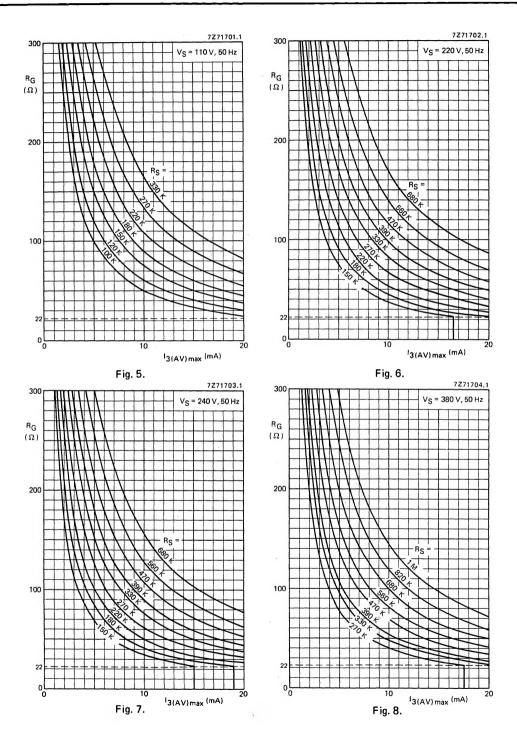
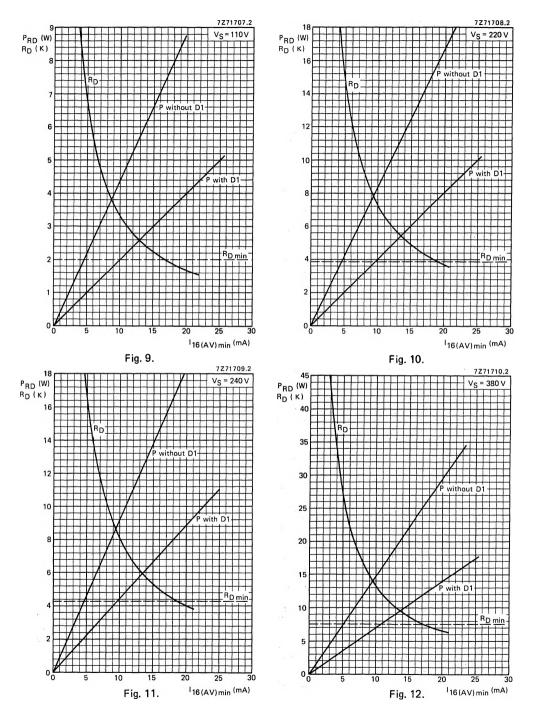


Fig. 4 Alternative supply arrangements.





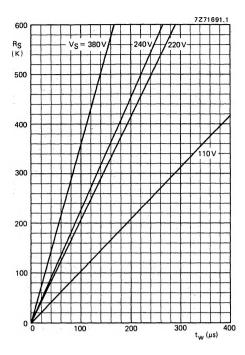


Fig. 13 Synchronization resistor R<sub>S</sub> as a function of required trigger pulse width  $t_W$  with mains voltage  $V_S$  as a parameter.

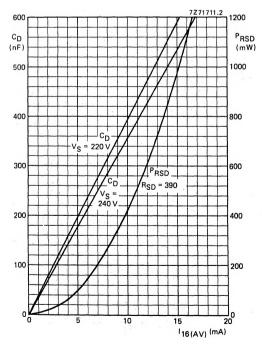


Fig. 14 Nominal value of voltage dropping capacitor  $C_D$  and power  $P_{RSD}$  dissipated in voltage dropping resistor  $R_{SD}$  as a function of the average supply current  $I_{16(AV)}$  with the mains supply voltage  $V_S$  as a parameter.

### **APPLICATION INFORMATION**

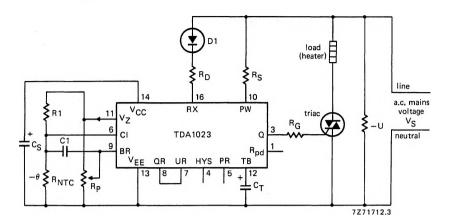


Fig. 15 The TDA1023 used in a 1200 to 2000 W heater with triac BT139. For component values see Table 3.

### **Conditions**

Mains supply:  $V_S = 220 \text{ V}$ Temperature range = 5 to 30 °C BT139 data:  $V_{GT} < 1.5 \text{ V}$   $I_{GT} > 70 \text{ mA}$  $I_L < 60 \text{ mA}$ 

Table 3	Temperature controller	component values	(see Fig.	15).
I able J.	I CITIDEI ALUI E COTTUOTICI	component values	(300 1 19.	10/.

parameter	symbol	value	remarks
Trigger pulse width	t <sub>W</sub>	75 μs	see BT139 data sheet
Synchronization resistor	$R_{S}$	180 kΩ	see Fig. 13
Gate resistor	$R_{G}$	110 Ω	see Fig. 6
Max. average gate current	<sup>1</sup> 3(AV)	4.1 mA	see Fig. 8
Hysteresis resistor	R4	n.c.	see Table 1
Proportional band resistor	R5	n.c.	see Table 1
Min. required supply current	<sup>I</sup> 16(AV)	11.1 mA	
Mains dropping resistor	R <sub>D</sub>	6.2 kΩ	see Fig. 10
Power dissipated in R <sub>D</sub>	P <sub>RD</sub>	4.6 W	see Fig. 10
Timing capacitor (eff. value)	CT	68 μF	see Table 2
Voltage dependent resistor	VDR	250 V a.c.	cat. no. 2322 593 6251
Rectifier diode	D1	BYW56	
Resistor to pin 11	R1	18.7 k $\Omega$	1% tolerance
NTC thermistor (at 25 °C)	RNTC	22 kΩ	B = 4200 K cat. no. 2322 642 1222
Potentiometer	Rp	22 k $\Omega$	
Capacitor between pins 6 and 9	C1	47 nF	
Smoothing capacitor	C <sub>S</sub>	220 μF; 16 V	- (c)
If $R_D$ and D1 are replaced by $C_D$ a	nd R <sub>SD</sub>		
Mains dropping capacitor	C <sub>D</sub>	470 nF	
Series dropping resistor	R <sub>SD</sub>	390 Ω	see Fig. 14
Power dissipated in R <sub>SD</sub>	PRSD	0.6 W	
Voltage dependent resistor	VDR	250 V a.c.	cat. no. 2322 594 6251

### Notes

## APPLICATION INFORMATION SUPPLIED ON REQUEST

<sup>1.</sup> ON/OFF control: pin 12 connected to pin 13.

<sup>2.</sup> If translation circuit is not required: slider of Rp to pin 7; pin 8 open; pin 9 connected to pin 11.