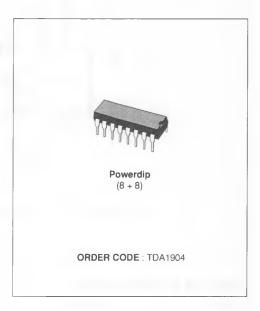


# **4 W AUDIO AMPLIFIER**

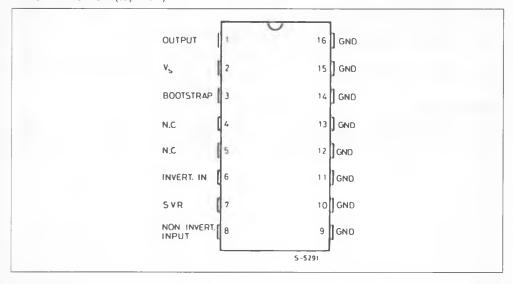
- HIGH OUTPUT CURRENT CAPABILITY (up to 2 A)
- PROTECTION AGAINST CHIP OVERTEM-PERATURE
- LOW NOISE
- HIGH SUPPLY VOLTAGE REJECTION
- SUPPLY VOLTAGE RANGE: 4 V TO 20 V



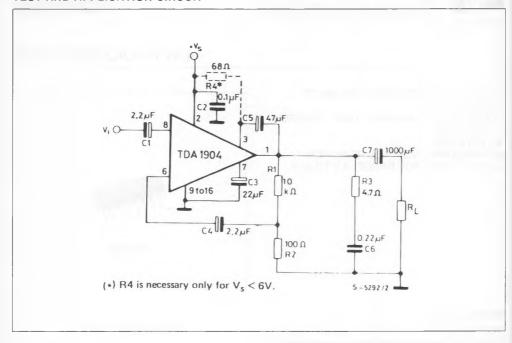
# **DESCRIPTION**

The TDA1904 is a monolithic integrated circuit in POWERDIP package intended for use as low-frequency power amplifier in wide range of applications in portable radio and TV sets.

## PIN CONNECTION (top view)



## **TEST AND APPLICATION CIRCUIT**



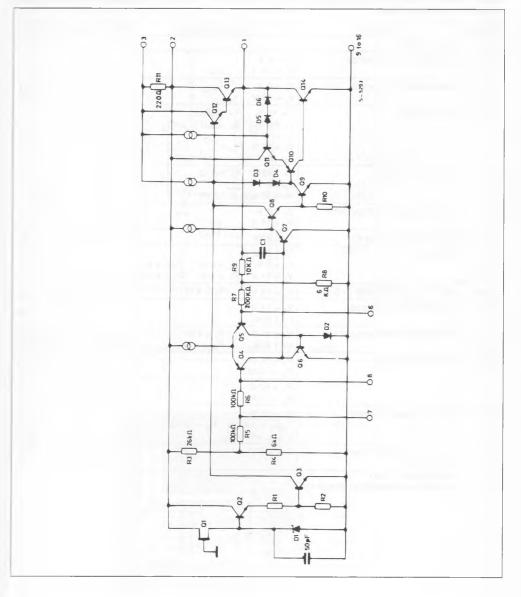
## **ABSOLUTE MAXIMUM RATINGS**

| Symbol                            | Parameter  | Value       | Unit |  |
|-----------------------------------|--|-------------|------|--|
| Vs                                | Supply Voltage   | 20          | V    |  |
| Io                                | Peak Output Current (non repetitive)   | 2.5         | Α    |  |
| Io                                | Peak Output Current (repetitive)   | 2           | Α    |  |
| P <sub>tot</sub>                  | Total Power Dissipation at $T_{amb} = 80  ^{\circ}\text{C}$<br>$T_{pins} = 60  ^{\circ}\text{C}$ | 1 6         | W    |  |
| T <sub>stg</sub> , T <sub>j</sub> | Storage and Junction Temperature   | - 40 to 150 | °C   |  |

## THERMAL DATA

| R <sub>th j-case</sub> | Thermal Resistance Junction-pins    | Max. | 15 | °C/W |
|------------------------|-------------------------------------|------|----|------|
| R <sub>th j-amb</sub>  | Thermal Resistance Junction-ambient | Max. | 70 | °C/W |

## **SCHEMATIC DIAGRAM**



**ELECTRICAL CHARACTERISTICS** (refer to the test circuit,  $T_{amb} = 25 \, ^{\circ}\text{C}$ ,  $R_{th}$  (heatsink) = 20  $^{\circ}\text{C/W}$ , unless otherwise specified)

| Symbol          | Parameter Test Conditions             |  |                        | Тур.         | Max.     | Unit |
|-----------------|---------------------------------------|--|------------------------|--------------|----------|------|
| Vs              | Supply Voltage                        |  |                        |              | 20       | V    |
| Vo              | Quiescent Output Voltage              | V <sub>s</sub> = 4 V<br>V <sub>s</sub> = 14 V  |                        | 2.1<br>7.2   |          | V    |
| I <sub>d</sub>  | Quiescent Drain Current               | V <sub>s</sub> = 9 V<br>V <sub>s</sub> = 14 V  |                        | 8<br>10      | 15<br>18 | mA   |
| Po              | Output Power                          |  | 1.8<br>4<br>3.1<br>0.7 | 2<br>4.5     |          | w    |
| d               | Harmonic Distortion                   | $f = 1 \text{ KHz}  R_L = 4 \Omega$<br>$V_S = 9 \text{ V}$<br>Po = 50  mW to  1.2  W   |                        | 0.1          | 0.3      | %    |
| Vi              | Input Saturation Voltage (rms)        | V <sub>s</sub> = 9 V<br>V <sub>s</sub> = 14 V  | 0.8                    |              |          | ٧    |
| Ri              | Input Resistance (pin 8)              | f = 1 KHz  | 55                     | 150          |          | kΩ   |
| η               | Efficiency                            |  |                        | 70<br>65     |          | %    |
| BW              | Small Signal Bandwidth (- 3 dB)       | V <sub>s</sub> = 14 V R <sub>L</sub> = 4 Ω   |                        | 40 to 40,000 |          | Hz   |
| G <sub>v</sub>  | Voltage Gain (open loop)              | V <sub>s</sub> = 14 V<br>f = 1 KHz   |                        | 75           |          | dB   |
| Gv              | Voltage Gain (closed loop)            | $ \begin{array}{cccccccccccccccccccccccccccccccccccc$  | 39.5                   | 40           | 40.5     | dB   |
| e <sub>N</sub>  | Total Input Noise                     | $R_0 = 50 \Omega$ $R_0 = 10 k\Omega$   |                        | 1.2<br>2     | 4        | μV   |
|                 |                                       | $R_g = 50 \Omega$ $R_g = 10 k\Omega$ (°°)  |                        | 2            |          | μV   |
| SVR             | Supply Voltage Rejection              | $\begin{aligned} &V_s = 12 \text{ V} \\ &f_{ripple} = 100 \text{ Hz}  R_g = 10 \text{ k}\Omega \\ &V_{ripple} = 0.5 \text{ V}_{rms} \end{aligned}$ | 40                     | 50           |          | dB   |
| T <sub>sd</sub> | Thermal Shut-down Case<br>Temperature | P <sub>tot</sub> = 2 W   |                        | 120          |          | ℃    |

Note: (') Weighting filter = curve A.

('') Filter with noise bendwidth: 22 Hz to 22 KHz.

Figure 1: Test and Application Circuit.

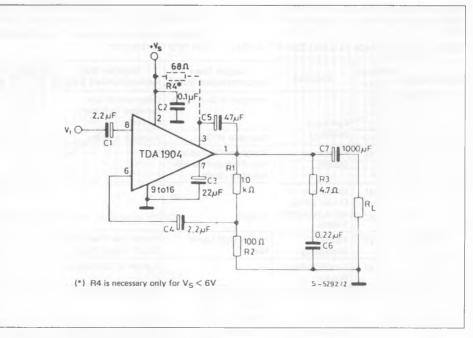
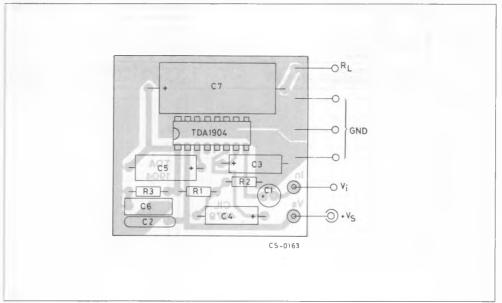


Figure 2 : P.C. Board and Components Layout of Figure 1 (1 : 1 scale).



#### **APPLICATION SUGGESTION**

The recommended values of the external components are those shown on the application circuit of fig. 1.

When the supply voltage  $V_S$  is less than 6 V, a 68  $\Omega$ 

resistor must be connected between pin 2 and pin 3 in order to obtain the maximum output power.

Different values can be used. The following table can help the designer.

|                | Reccom.<br>Value | Purpose  | Larger than<br>Recommended Value                                | Smaller than  | Allowed          | Range  |
|----------------|------------------|--|---|---|------------------|--------|
| Components     |                  |  |   | Recommended Value                                   | Min.             | Max.   |
| R <sub>1</sub> | 10 kΩ            | Feedback   | Increase of Gain.   | Decrease of Gain.<br>Increase Quiescent<br>Current. | 9 R <sub>3</sub> |        |
| R <sub>2</sub> | 100 Ω            | Resistors  | Decrease of Gain.   | Increase of Gain.                                   |                  | 1 kΩ   |
| R <sub>3</sub> | 4.7 Ω            | Frequency<br>Stability   | Danger of Oscillation at High Frequencies with Inductive Loads. |   |                  |        |
| R <sub>4</sub> | 68 Ω             | Increase of the<br>Output Swing<br>with Low Supply<br>Voltage. |   |   | 39 Ω             | 220 Ω  |
| C <sub>1</sub> | 2.2 μF           | Input DC<br>Decoupling.  | Higher Cost Lower<br>Noise.                                     | Higher Low Frequency<br>Cutoff. Higher Noise.       |                  |        |
| C <sub>2</sub> | 0.1 μF           | Supply Voltage<br>Bypass.                                      |   | Danger of Oscillations.                             |                  |        |
| C <sub>3</sub> | 22 μF            | Ripple Rejection   | Increase of SVR<br>Increase of the<br>Switch-on Time.           | Degradation of SVR.                                 | 2.2 μF           | 100 μF |
| C <sub>4</sub> | 2.2 μF           | Inverting Input DC Decoupling.                                 | Increase of the<br>Switch-on Noise                              | Higher Low Frequency Cutoff.                        | 0.1 μF           |        |
| C <sub>5</sub> | 47 μF            | Bootstrap.   |   | Increase of the Distortion at Low Frequency.        | 10 μF            | 100 μF |
| C <sub>6</sub> | 0.22 μF          | Frequency<br>Stability.  |   | Danger of Oscillation.                              |                  |        |
| C <sub>7</sub> | 1000 μF          | Output DC<br>Decoupling.                                       |   | Higher Low Frequency Cutoff.                        |                  |        |

Figure 3 : Quiescent Output Voltage vs. Supply Voltage.

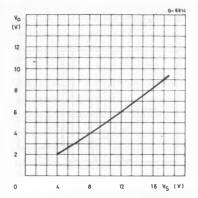


Figure 5 : Output Power vs. Supply Voltage.

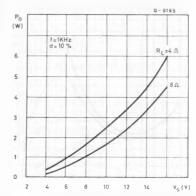


Figure 7: Distortion Output Power.

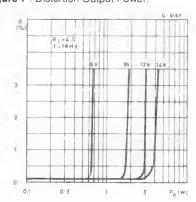


Figure 4 : Quiescent Drain Current vs. Supply Voltage.

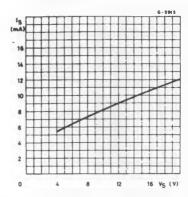


Figure 6: Distortion vs. Output Power.

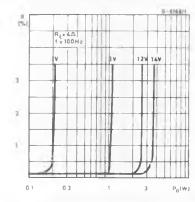


Figure 8: Distortion vs. Output Power.

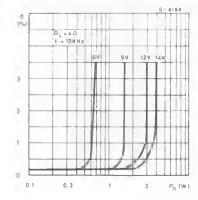


Figure 9 : Distortion vs. Output Power.

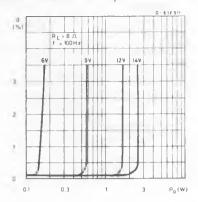


Figure 11: Distortion vs. Output Power.

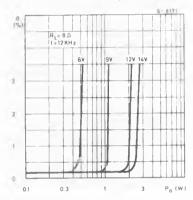


Figure 13: Distortion vs. Frequency.

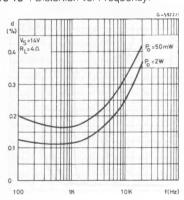


Figure 10 : Distortion vs. Output Power.

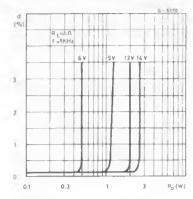


Figure 12: Distortion vs. Frequency.

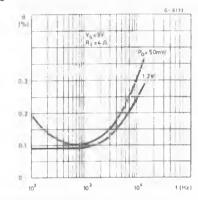


Figure 14: Distortion vs. Frequency.

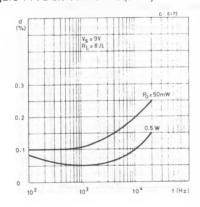


Figure 15: Distortion vs. Frequency.

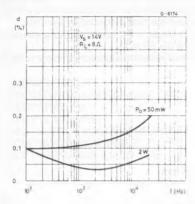


Figure 17: Total Power Dissipation and Efficiency vs. Output Power.

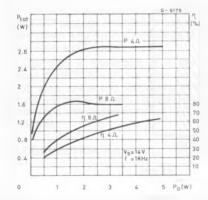


Figure 19: Total Power Dissipation vs. Output Power.

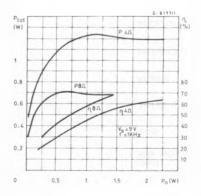


Figure 16 : Supply Voltage Rejection vs. Frequency.

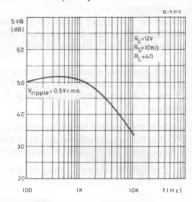


Figure 18 : Total Power Dissipation vs. Output Power.

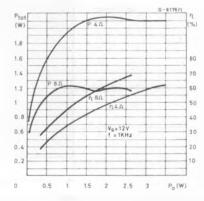
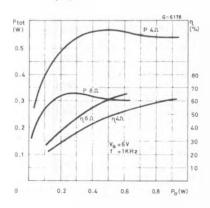


Figure 20 : Total Power Dissipation vs. Output Power.



## THERMAL SHUT-DOWN

The presence of a thermal limiting circuit offers the following advantages:

- An overload on the output (even if it is permanent), or an above limit ambient temperature can be easily tolerated since the T<sub>j</sub> cannot be higher than 150 °C.
- 2) The heatsink can have a smaller factor of safety compared with that of a conventional circuit. There is no possibility of device damage due to high junction temperature.

If for any reason, the junction temperature increase up to 150 °C, the thermal shut-down simply reduces the power dissipation and the current consumption.

#### MOUNTING INSTRUCTION

The TDA1904 is assembled in the Powerdip, in which 8 pins (from 9 to 16) are attached to the frame and remove the heat produced by the chip.

Figure 21 shows a PC board copper area used as a heatsink (I = 65 mm).

The thermal resistance junction-ambient is 35 °C.

Figure 21: Example of Heatsink Using PC Board Copper (I = 65 mm).

